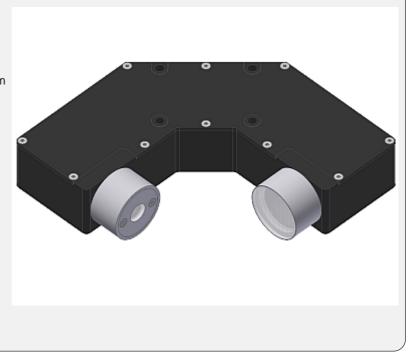
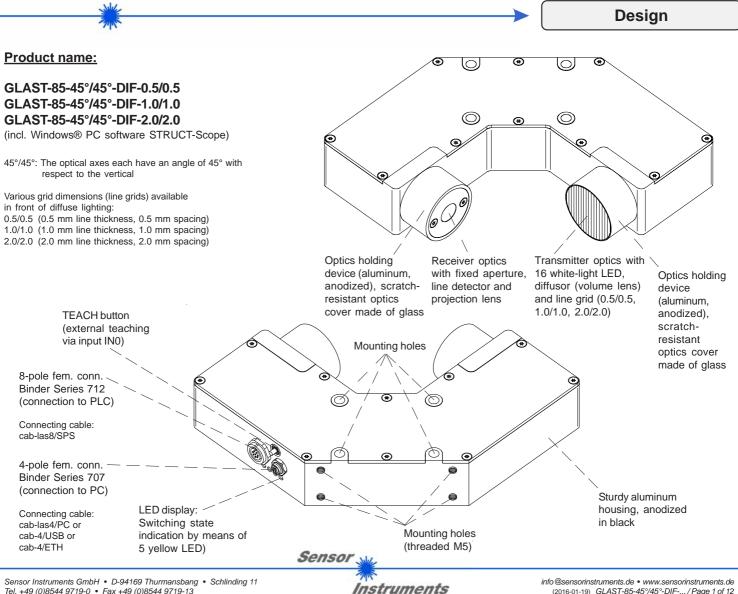
# **GLAST** Series

## GLAST-85-45°/45°-DIF-...

- Recommended measurement distance: 85 mm ± 2 mm
- Determination of the direct reflection behaviour of glossy objects by way of spatial frequency analysis (frequency and amplitude) of a line grid
- Diffuse lighting with three different line grids available (0.5/0.5, 1.0/1.0 or 2.0/2.0)
- Up to 31 states can be saved
- Line detector (512 pixel) incl. projection lens
- RS232 interface (USB or Ethernet adapter is available)
- Haze control
- Brightness correction can be activated (STAT/DYN)
- Several TEACH functions (via PC, PLC, or push button)
- Various evaluation algorithms can be activated
- "BEST HIT" mode
- Switching state display by means of 5 yellow LEDs
- Parameterizable via Windows® software
- Temperature compensated
- Sturdy aluminum housing





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(2016-01-19) GLAST-85-45°/45°-DIF-... / Page 1 of 12

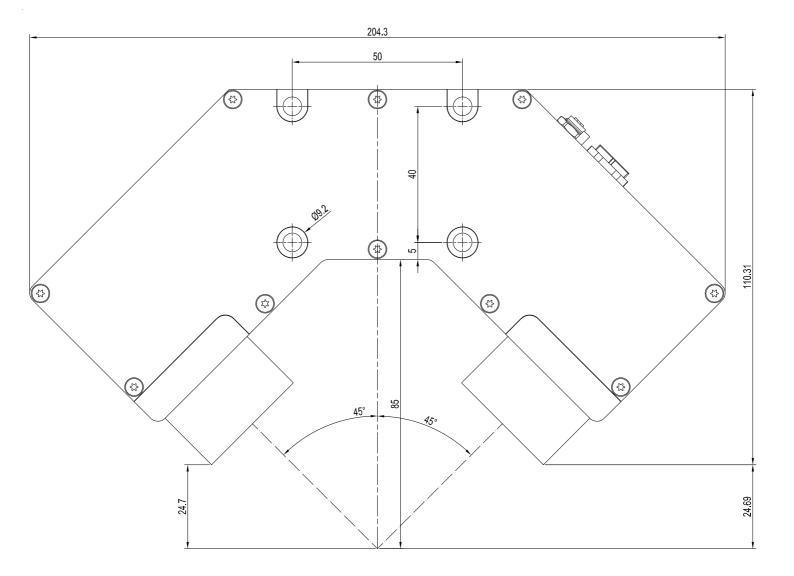
Super	
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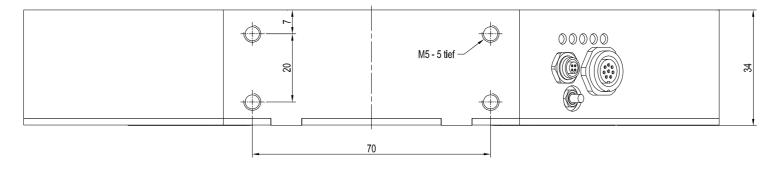
**Technical Data** 

+24VDC (± 10%), reverse polarity protected, overcurrent protected	
< 500 mA	
100 mA, short circuit proof	
5 yellow LED visualize the physical state of the outputs OUT0 OUT4	
1 digital input: IN0 (Pin 3), digital (0V/+24V)	
OUT0OUT4 (Pin 48): digital (0V/+24V), pn-/pnp-able (bright-/dark-switching, can be switched)	
R\$232	
100 ms 1 s (adjustable via PC software)	
max. 32 values (adjustable via PC software)	
Various line grids available: GLAST-85-45°/45°-DIF-0.5/0.5: Line grid with 0.5 mm line thickness and 0.5 mm spacing GLAST-85-45°/45°-DIF-1.0/1.0: Line grid with 1.0 mm line thickness and 1.0 mm spacing GLAST-85-45°/45°-DIF-2.0/2.0: Line grid with 2.0 mm line thickness and 2.0 mm spacing	
typ. 10 Hz	
The optical axes are inclined each at an angle of 45° from the normal (vertical)	
typ. 85 mm ± 5 mm	
16 super-bright white-light LED, diffusor (volume lens) and line grid	
Can be switched via PC software: AC operation (LED MODE-AC), DC operation (LED MODE-DC),	
line detector (512 pixel), projection lens, circular aperture (Ø 1 mm)	
adjustable via PC software (EXPOSURE TIME)	
Measuring length typ. 20 mm at a distance of 85 mm	
$\Delta X/\Delta T$ ; $\Delta Y/\Delta T$ typ. 0,2 digits/°C (< 0,01% / °C)	
20mm/4096	
5 spatial frequency spectrums (max. 31 states)	
LxWxH approx. 204.3 mm x 110.31 mm x 34 mm, without connectors	
Aluminum, anodized in black (optics holding device: aluminum, anodized)	
IP64	
to PLC: cab-las8/SPS or cab-las8/SPS-w to PC/RS232 interface: cab-las4/PC or cab-las4/PC-w alternatively: to PC/USB interface: cab-4/USB or cab-4/USB-w alternatively: to PC/Ethernet interface: cab-4/ETH	
Connection to PLC: 8-pole fem. connector (Binder 712), connection to PC: 4-pole fem. connector (Binder 707)	
Operating temperature range: -20°C +55°C, storage temperature range: -20°C +85°C	

Sensor W

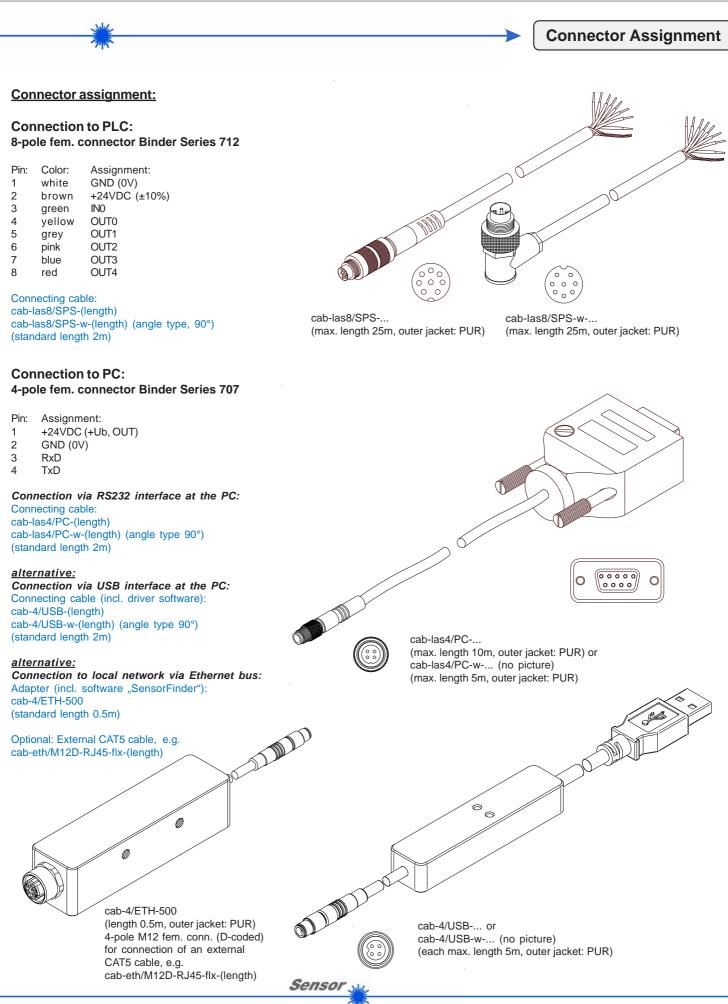






All dimensions in mm

Sensor



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**Fields of Application** 

#### Fields of application of the sensors of GLAST series:

Inline sensors of the GLAST series primarily are used for the inspection of highly reflecting surfaces (e.g. stainless steel panels, aluminum sheets, painted surfaces, plastic films) and transparent objects (films, glass plates, plexiglass plates).

A projection lens projects a line grid onto a line detector with the help of the object to be inspected, which functions as a more or less optimal mirror. Transparent objects are placed close to the line grid, which again is projected onto a line detector by a projection lens. In both cases the quality of the object determines the quality of the video signal at the line detector.

The reflective method operates at an angle of 30° (respectively 45°) each of the optical axes of the transmitter and receiver branch from the vertical, whereas in the through-beam method the object to be inspected stands vertically to the optical axis of the transmitterreceiver setup. In both cases the transmitter-receiver distance is approx. 135 mm.

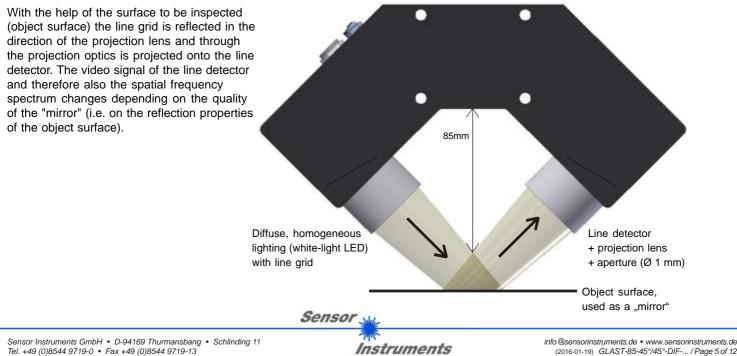
Three different line grids are available in each case (0.5m/0.5mm, 1.0mm/1.0mm, and 2.0mm/2.0mm).



#### Measuring principle of the GLAST series sensors:

The GLAST sensor (GLoss And STructure) among others was developed to inspect the haze behaviour of objects. For this purpose a line grid is placed in front of a homogeneously illuminated area. A projection lens projects this line grid onto the line detector, and the object to be inspected practically functions as a mirror (reflector). The video signal that is available at the receiver side then provides information about the quality of the "mirror", i.e. about the reflection properties of the object surface. If the haze ratio increases, the video signal "flattens", which also results in a change of the spatial frequency spectrum, the line grid that is projected on the line detector. This means that the higher frequencies are less present, and the amplitudes generally decrease.

The GLAST sensor in principle is a line camera that is equipped with a controllable diffuse light unit (16 white light LED + diffusor + line grid). The detection range (line) is 20 mm at a distance of 85 mm from the sensor body (see dimensions) and runs in longitudinal extension of the sensor. The line-shaped section of the surface to be inspected (approx. 20 mm x 0.5 mm) is projected onto the line detector by the projection lens (receiver optics). The video signal that is generated by the line detector is converted into a spatial frequency spectrum by way of suitable algorithms in the sensor's internal controller. This means that a signal is thus available that provides information about the haze ratio of the surface. Up to 5 spatial frequency spectrums and up to 31 states can be saved in the sensor. During the inspection process the current spatial frequency spectrum is compared with the spatial frequency spectrums saved in the memory, and the most similar spatial frequency spectrum is searched. Amplitudes, frequency, and harmonic waves also are compared.



Instruments



#### Visualization of the state code:

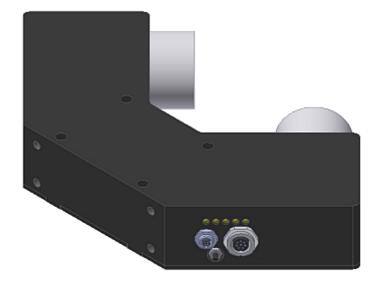
The state code is visualized by means of 5 yellow LEDs at the housing of the GLAST sensor. The state code that is indicated at the LED display simultaneously is provided in binary mode (OUT BINARY) as 5-bit binary information at digital outputs OUT0 ... OUT4 of the 8-pole PLC connector.

The GLAST sensor is able to process a maximum of 31 states (code 0 ... 30) corresponding to the individual rows in the TEACH TABLE. The sensor indicates an "error" or a "not detected state" by turning on all the LEDs (digital outputs OUT0 ... OUT4 at HIGH level).

Besides, the sensor can store a maximum of 5 spatial frequency spectrums for correlation evaluation.

A maximum of 5 teach states (no. 0, 1, 2, 3, 4) are permitted in DIRECT mode (OUT DIRECT HI or OUT DIRECT LO). If the selector switch is set to DIRECT HI, the corresponding digital output is HI and the other four are LO. If no state was detected, the digital outputs are in LO state (no LED is on).

If the selector switch is set to DIRECT LO, the corresponding digital output is LO and the other four are HI. If no state was detected, the digital outputs are in HI state (all LEDs are on).



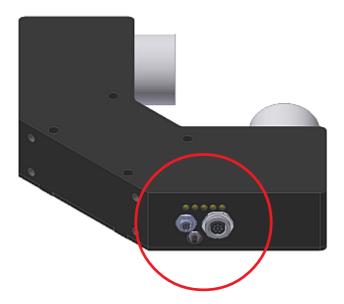


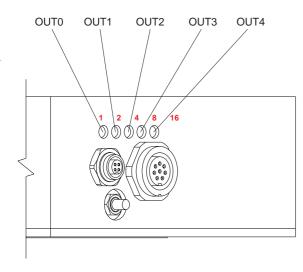
#### GLAST Series • Sensors for gloss and structure detection

#### LED display:

The state code is visualized by means of 5 yellow LEDs at the housing of the GLAST sensor. The state code indicated at the LED display is output as 5-bit binary information at the digital outputs OUT0 ... OUT4 of the 8-pole PLC connector.

In the DIRECT mode the maximum number of state codes to be taught is 5. These 5 state codes can be directly output at the 5 digital outputs. The respective detected state code is displayed by means of the 5 yellow LEDs at the housing of the GLAST sensor.





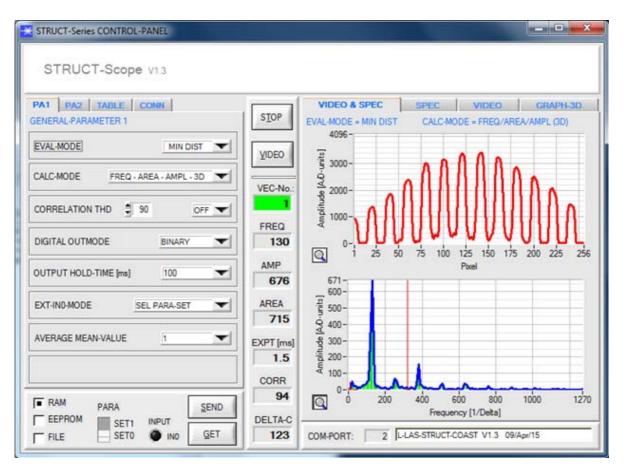
	→	ED Display
00000	●○○○○ 1	○○○○○ 2
●●○○○ 3	00 <b>0</b> 00 4	●○●○○ 5
○ <mark>● ●</mark> ○ ○ 6	••••• 7	000 <b>0</b> 0 8
<b>9</b> 0000	○●○●○ 10	•••• 11
○○●●○ 12	●○●●○ 13	○ <b>●●</b> ●○ 14
●●●●○ 15	0000 <mark>0</mark> 16	●○○○● 17
○●○○● 18	<b>•</b> •••• 19	○○●○● 20
●○●○● 21	○●●○● 22	<b>2</b> 3
○○○●● 24	●○○●● 25	○●○●● 26
<b>0 0 0 0 0 0 0 0 0 0</b>	○○●●● 28	<b>0</b> 0 <b>00</b> 29
○ ● ● ● ● 30	Fehler bzw. "nicht erkannt"	



- MAN

#### Parameterization

#### Software STRUCT-Scope: GENERAL-PARAMETER 1 and VIDEO & SPEC



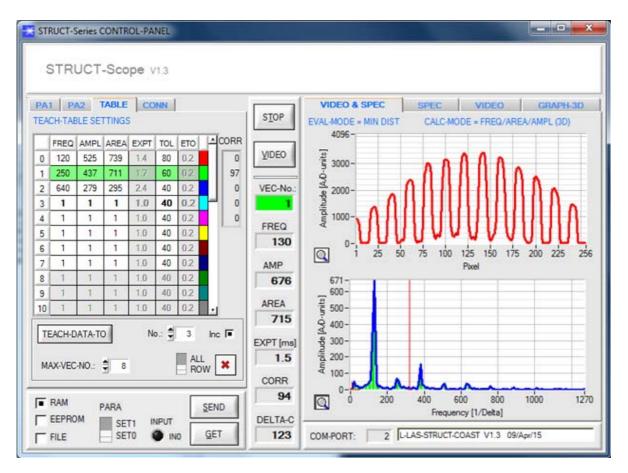
The RS232 interface (tabs PA1, PA2, and TABLE) is used to set sensor parameters such as:

EVAL-MODE: CALC-MODE:	Evaluation mode in the 2D/3D number range Calculation mode of information from the spectrum
CORRELATION THD:	Threshold for use in correlation calculation
DIGITAL OUTMODE:	Control mode of digital outputs
OUTPUT HOLD-TIME:	Output hold time
EXT-IN0-MODE:	Setting of the external trigger mode.
	(CONTINUOUS, TRIGG-IN0 L/H, TRIGG IN0 HIGH, SEL PARA-SET)
AVERAGE MEAN-VALUE:	Setting of averaging at the sensor (possible values: 1, 2,4,8,16 or 32)



Parameterization

#### Software STRUCT-Scope: TEACH-TABLE



#### TEACH-TABLE:

Maximum of 31 structure vectors (vector entries) for the differentiation of 31 different structures, setting of tolerances for the evaluation values (TOL) from the spectrum, and setting of the tolerance for the exposure time (ETO). Display of the correlation value **for max. 5 comparison spectrums** (spatial frequency spectrums). TEACH-IN button for teaching the current spectrum to the teach table.

Display and input of the following evaluation values:

- FREQ: Frequency
- AMPL: Amplitude
- AREA: Normed area ratio calculated from the frequency spectrum
- EXPT: Exposure time of the respective structure
- TOL: Tolerance for frequency and amplitude
- ETO: Tolerance for exposure time





#### Firmware update by means of the software "FirmwareLoader":

FIRMWARE LOADER V1.1					
ESTABLISH CONNECTION					
SELECT COMPORT [1256]	TRY TO CONNECT				
FIRMWARE UPDATE					
READ FIRMWARE FROM DISK	CLEAR WINDOW				
ARM FIRMWARE LOADER	DISARM FIRMWARE LOADER				
IT IS STRONGLY RECOMMENDED TO UPDATE THE FIRMWARE ACCORDING TO THE MANUAL!					
SPECTRO3 V4.0 RT May 09 2012					
	<u>×</u>				
CREATE EEPROM BACKUP					
READ EEPROM DATA FROM SENSOR	SAVE EEPROM DATA TO SENSOR				
EEPROM TRANSFER FILE d:\BackupFiles\EEP	EEPROM TRANSFER FILE d:\BackupFiles\EEPROM_Backup 1131.dat				

The software "Firmware Loader" allows the user to perform an automatic firmware update. The update will be carried out through the RS232 interface.

An initialisation file (xxx.ini) and a firmware file (xxx.elf.S) are required for performing a firmware update. These files can be obtained from your supplier. In some cases an additional firmware file for the program memory (xxx.elf.p.S) is also needed, and this file will be automatically provided together with the other two files.

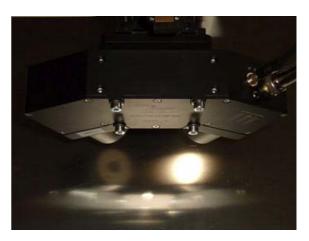




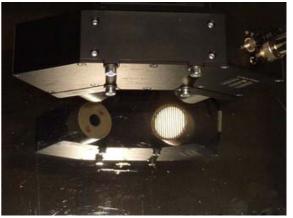
#### Haze control of stainless steel plates

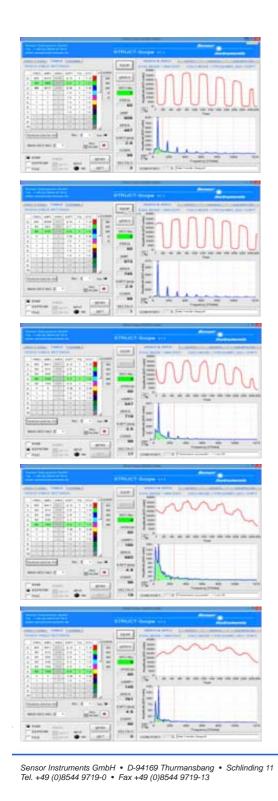
The haze of stainless steel surfaces should be controlled. For this purpose an optical sensor type GLAST-85-30°/30°-DIF-2.0/2.0 is used. At this, the distance to the stainless steel surface is approximately 85 mm and the detected line has a length of around 20 mm at this distance. The haze can be proper detected, as shown in the screen shots.











Instruments

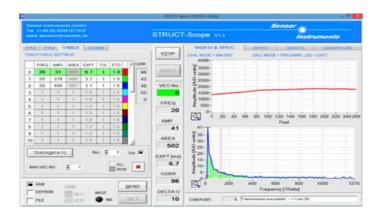
Sensor

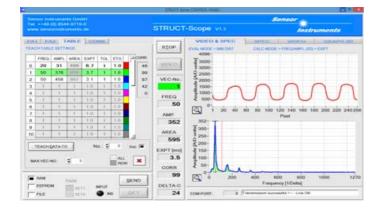
info@sensorinstruments.de • www.sensorinstruments.de (2016-01-19) GLAST-85-45°/45°-DIF-.../Page 11 of 12 (1189.00) Subject to alteration

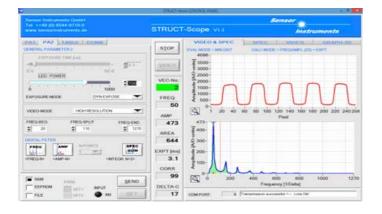


### Differentiation of diverse hazy metal parts

Diverse hazy metal components should be differentiated. For this purpose, a haze sensor type GLAST-85-30°/30°-DIF-1.0/1.0 is used. At this, the sensor is arranged at a distance of around 85 mm to the object. Furthermore, the detecting range is approximately 20 mm in length. The metal parts can be proper haze differentiated as shown in the screen shots.















Sensor M.