



1. Ball joint coating control

The joint ball surface should be controlled with a view to the coating. At this, uncoated joint balls should be differentiated from coated and blue coated joint balls. For this purpose, a color sensor type **SPECTRO-3-5-DIF-JR** is used at a distance of approximately 5mm to the object. The detecting range at this distance is around 5mm. The respective coating can be proper detected as shown in the screen shots.

